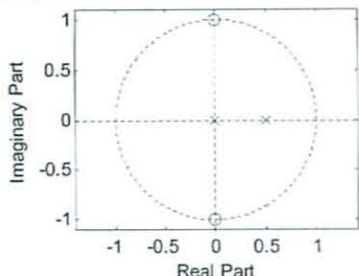


EE-3220-11 - Dr. Durant - Quiz 6
Winter 2014-'15, Week 6

1. (2 points) Make a list of zeros and a list of poles given this z-plane view of a system H(z).



zeros
 j
 $-j$

poles
 $1/2$
 $-1/2$

$(-1/2)$ reverse zrp

2. (2 points) Given the roots you listed above, write out H(z). Fully expand the numerator and the denominator.

$$H(z) = \frac{(z-j)(z+j)}{z(z-1/2)} = \frac{z^2+1}{z^2-1/2z} = \frac{1+z^{-2}}{1-1/2z^{-1}}$$

3. (2 points) Recall that $H(z) = Y(z) / X(z)$. Take the inverse z-transform of your result in 2 and solve for y(n) to determine the difference equation that implements the system H(z).

$$Y(z)(1 - \frac{1}{2}z^{-1}) = X(z)(1 + z^{-2})$$

$$y(n) - \frac{1}{2}y(n-1) = x(n) + x(n-2]$$

$$y(n) = \frac{1}{2}y(n-1) + x(n) + x(n-2]$$

(1/4) y(n-1) on wrong side

4. (2 points) A voice signal sampled at 16 kHz is intermittently jammed with a loud, 2 kHz tone. Begin the design an IIR notch filter to suppress this tone. What are the radii and angles of the poles and zeros? Present angles in terms of π (e.g., 0.7π).

$$F_s = 16 \text{ kHz}$$

$$F = 2 \text{ kHz}$$

$$\omega = \frac{F}{F_s} \cdot 2\pi = \frac{2}{16} \cdot 2\pi = \frac{\pi}{4}$$

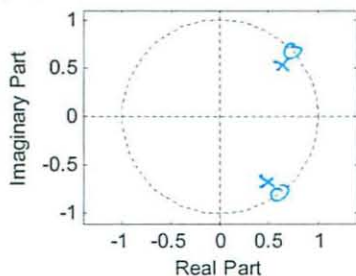
zeros
 $|\angle \pm \frac{\pi}{4}$

poles
 $0.99 \angle \pm \frac{\pi}{4}$
close to bot \angle

$(1/4)$ $\text{Phase} \pm$

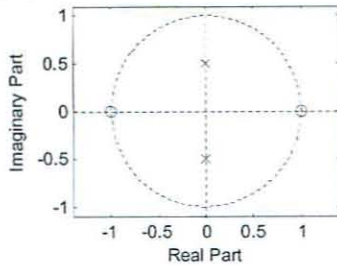
$(-3/4)$ for poles not close

5. (2 points) Using the zeros and poles you calculated for your notch filter, complete this zero-pole plot.



EE-3220-21 - Dr. Durant - Quiz 6
Winter 2014-'15, Week 6

1. (2 points) Make a list of zeros and a list of poles given this z-plane view of a system $H(z)$.



zeros
1
-1

poles
 $j/2$
 $-j/2$

(-1) reverse ztp

2. (2 points) Given the roots you listed above, write out $H(z)$. Fully expand the numerator and the denominator.

$$H(z) = \frac{(z-1)(z+1)}{(z-j/2)(z+j/2)} = \frac{z^2-1}{z^2+1/4} = \frac{1-z^{-2}}{1+1/4z^{-2}}$$

3. (2 points) Recall that $H(z) = Y(z) / X(z)$. Take the inverse z-transform of your result in 2 and solve for $y(n)$ to determine the difference equation that implements the system $H(z)$.

$$Y(z)(1+1/4z^{-2}) = X(z)(1-z^{-2})$$

$$y(n) + 1/4y(n-2) = x(n) - x(n-2)$$

$$y(n) = -1/4y(n-2) + x(n) - x(n-2)$$

$(-1/4)$ $y(n-2)$ on wrong side

4. (2 points) A voice signal sampled at 6 kHz is intermittently jammed with a loud, 2 kHz tone. Begin the design an IIR notch filter to suppress this tone. What are the radii and angles of the poles and zeros? Present angles in terms of π (e.g., 0.7π).

$$f_s = 6 \text{ kHz}$$

$$F = 2 \text{ kHz}$$

$$\omega = \frac{F}{f_s} \cdot 2\pi = \frac{2}{6} \cdot 2\pi = \frac{2\pi}{3}$$

zeros
 $1 \angle \pm \frac{2\pi}{3}$

poles
 $0.99 \angle \pm \frac{2\pi}{3}$

\uparrow close to bot < 1

$(-1/4)$ no \pm
 $(-3/4)$ poles not close

5. (2 points) Using the zeros and poles you calculated for your notch filter, complete this zero-pole plot.

